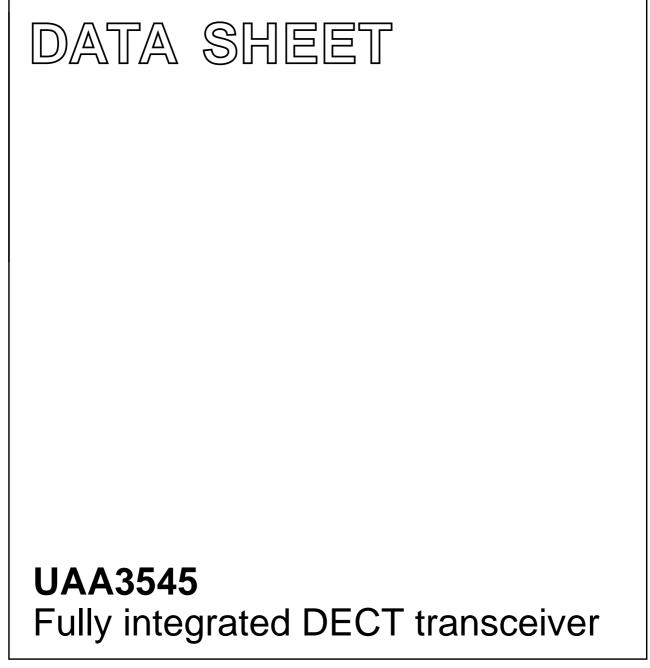
# INTEGRATED CIRCUITS



Product specification File under Integrated Circuits, IC17 2001 Sep 06



HILIP

# UAA3545

### FEATURES

- Economical solution for a radio in DECT cordless telephones
- Integrated low phase noise VCO with no production tuning required
- · Fully integrated receiver with high sensitivity
- Dedicated DECT PLL synthesizer
- · 3 dBm output preamplifier with an integrated switch
- 3-line serial interface bus
- Low current consumption from a 3.2 V supply
- Compatible with Philips Semiconductors baseband chips (PCD509xx and PCD80xxx)
- Reduced number of control signals.

### APPLICATIONS

• DECT cordless telephones: 1880 to 1930 MHz.

### **GENERAL DESCRIPTION**

The UAA3545 BiCMOS device is a low power, highly integrated circuit, for Digital Enhanced Cordless Telecommunication (DECT) applications.

It features a fully integrated receiver, from antenna filter output to the demodulated data output, a fully integrated VCO, a synthesizer to implement a phase-locked loop for DECT channel frequencies and a TX preamplifier to drive the external transmit power amplifier (CGY20xx series or UAA359x series of Philips integrated circuits). The synthesizer's main divider is driven by the prescaler output in the range of 1880 to 1930 MHz and is programmed via a 3-wire serial bus. The reference divider ratio is programmable to 4, 8, 12 or 16. Outputs of the main and reference dividers drive a phase comparator where a charge pump produces phase error current pulses for integration in an external loop filter (only a passive loop filter is necessary). The charge-pump current is set to 4 mA for fast switching.

The VCO is powered from an internally regulated voltage source and includes integrated variable capacitance diodes and integrated coils. Its tuning range is guaranteed. The VCO and the synthesizer are switched-on one slot before the active slot to lock the VCO to the required channel frequency. Immediately before the active slot, the synthesizer is switched-off to allow open loop modulation of the VCO during transmission. When opening the loop, frequency pulling (due to switching-off the synthesizer) can be maintained within the DECT specification.

The device is designed to operate from a 3.2 V nominal supply. Separate power and ground pins are provided for the different sections of the circuit. Ground leads should be short-circuited externally to prevent large currents flowing across the die and causing damage. All V<sub>CC</sub> supplies (V<sub>CC(REG)</sub>, V<sub>CC(SYN)</sub>, V<sub>CC(RX)</sub> and V<sub>CC(TX)</sub>) must be at the same potential (V<sub>CC</sub>).

### **ORDERING INFORMATION**

TYPE PACKAGE							
NUMBER	NAME	DESCRIPTION	VERSION				
UAA3545HL	LQFP32	plastic low profile quad flat package; 32 leads; body $5 \times 5 \times 1.4$ mm	SOT401-1				

# UAA3545

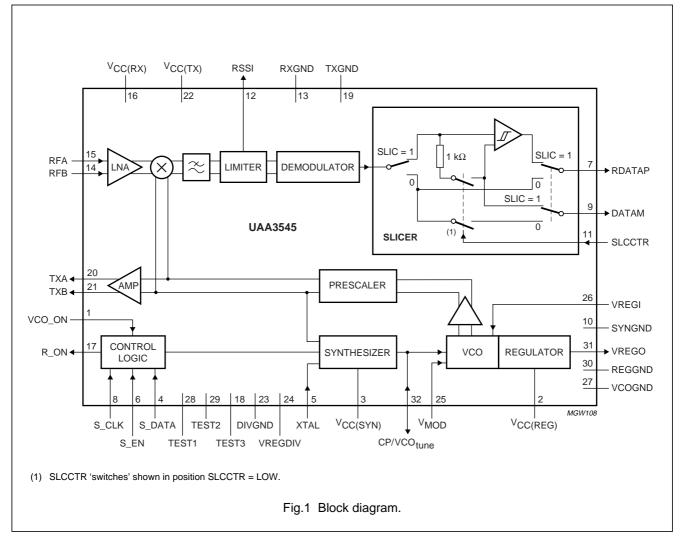
### QUICK REFERENCE DATA

 $V_{CC}$  = 3.2 V;  $T_{amb}$  = 25 °C; characteristics with a typical value only are not tested; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
$V_{CC(syn)}, \\ V_{CC(reg)}, \\ V_{CC(RX)}, \\ V_{CC(TX)}$	supply voltage	All $V_{CC}$ supplies must be at the same potential ( $V_{CC}$ )	3.0	3.2	3.6	V
I <sub>CC(SYN)</sub>	synthesizer supply current	synthesizer ON	-	5	7	mA
I <sub>CC(REG)</sub>	VCO, buffer and prescaler regulator supply current	VCO ON	_	14	17	mA
I <sub>CC(RX)</sub>	receiver supply current		-	36	44	mA
I <sub>CC(TX)</sub>	transmit preamplifier supply current		-	12	15	mA
I <sub>CC(pd)</sub>	total supply current in Power-down mode		-	10	100	μA
f <sub>o(RF)</sub>	RF output frequency		1880	-	1930	MHz
f <sub>(i)XTAL</sub>	crystal reference input frequency		-	3.456, 6.912, 10.368 or 13.824	-	MHz
f <sub>PC</sub>	phase comparator frequency		-	864	_	kHz
T <sub>amb</sub>	ambient temperature		-10	_	+60	°C

# UAA3545

# **BLOCK DIAGRAM**

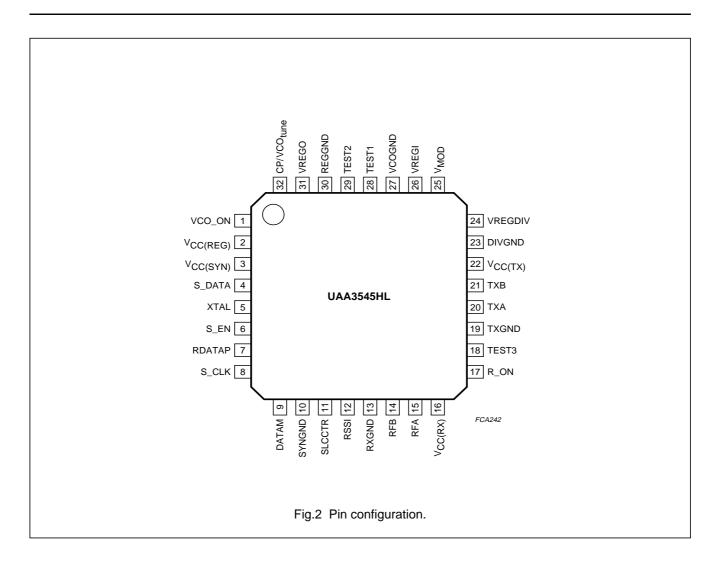


# PINNING

SYMBOL	PIN	DESCRIPTION
VCO_ON	1	VCO section power-on control; note 1
V <sub>CC(REG)</sub>	2	regulator positive supply voltage
V <sub>CC(SYN)</sub>	3	synthesizer positive supply voltage
S_DATA	4	3-wire bus data signal input
XTAL	5	reference frequency input; note 2
S_EN	6	3-wire bus enable signal input
RDATAP	7	demodulator output voltage
S_CLK	8	3-wire bus clock signal input
DATAM	9	switched demodulator output voltage
SYNGND	10	synthesizer ground
SLCCTR	11	DATAM switch control signal (see Fig.1)
RSSI	12	received signal strength intensity voltage output
RXGND	13	receiver ground
RFB	14	received signal input B
RFA	15	received signal input A
V <sub>CC(RX)</sub>	16	receiver positive supply voltage
R_ON	17	receiver power-on control; note 3
TEST3	18	TEST input 3 (must be connected to GND)
TXGND	19	transmitter ground
TXA	20	transmit amplifier output A
ТХВ	21	transmit amplifier output B
V <sub>CC(TX)</sub>	22	transmitter positive supply voltage
DIVGND	23	divider ground
VREGDIV	24	divider regulated supply voltage
V <sub>MOD</sub>	25	VCO analog modulation voltage input
VREGI	26	VCO regulated voltage input
VCOGND	27	VCO ground
TEST1	28	TEST input 1 (must not be connected)
TEST2	29	TEST input 2 (must not be connected)
REGGND	30	regulator ground
VREGO	31	VCO section regulated voltage output
CP/VCO <sub>tune</sub>	32	charge-pump output/VCO tuning input

### Notes

- 1. Corresponds to the S\_PWR of the baseband chip (see Section "Operating modes" for more details).
- 2. Corresponds to the REF\_CLK of the baseband chip.
- 3. See Section "Operating modes" for more details.



# FUNCTIONAL DESCRIPTION

### Transmit chain

### VCO AND PRESCALER

The fully integrated VCO operates at a multiple of the DECT frequency. It is supplied by an on-chip voltage regulator to minimize frequency disturbances due to supply voltage variations. The VCO signal is fed into a prescaler. A large difference between transmitted and VCO frequencies reduces transmitter-oscillator coupling problems.

The output of the prescaler drives the synthesizer main divider. The divider output can also be switched to either the TX preamplifier or the RX LO output buffer. The high isolation obtained from the prescaler ensures very small frequency changes when turning-on the TX preamplifier or the RX section. In TX mode, the oscillator can be modulated directly with GFSK-filtered data at pin V<sub>MOD</sub>.

### TX PREAMPLIFIER

The TX preamplifier amplifies the RF signal to a level of 3 dBm (typical) which is suitable for use with Philips Semiconductors DECT power amplifiers.

### Synthesizer

### MAIN DIVIDER

The main divider is clocked by the RF signal from the prescaler at frequencies from 1880 to 1930 MHz. Any main divider ratio from 2176 to 2303 inclusive can be programmed.

### REFERENCE DIVIDER

The reference divider is clocked by the signal at pin XTAL. The circuit operates with levels from 1.2 to 1.8 V (p-p) at a frequency of 3.456 MHz. By programming the 'REFD' bits of the serial input register (see Table 1) the reference frequency can be set for 6.912, 10.368 or 13.864 MHz.

### PHASE COMPARATOR

The phase comparator is driven by the output of the main and reference dividers. It produces current pulses at pin CP/VCO<sub>tune</sub>, the pulse duration being the difference in arrival time of current pulse edges from the two dividers. If the main divider edge arrives first, pin CP sinks current. If the reference divider edge arrives first, pin CP sources current. The DC value of the charge-pump current is defined by an internal resistor. Additional circuitry is included to ensure the gain of the phase detector remains linear even for small phase errors.

### Serial programming bus

A simple 3-line unidirectional serial bus is used to program the circuit. The three lines are data (S\_DATA), serial clock (S\_CLK) and serial bus enable (S\_EN). Data sent to the device are loaded in bursts framed by S\_EN. Programming clock edges and their appropriate data bits are ignored until S\_EN goes active (LOW). The programmed information is read directly by the main divider when S\_EN returns to HIGH. S\_DATA and S\_EN change value on the falling edge of S\_CLK.

During synthesizer operation, S\_EN should be held HIGH. Only the last 24 bits clocked into the device are retained within the serial register. Additional leading bits are ignored and no check is made on the number of clock pulses. The data format is shown in Table 1. The first bit entered is b23, the last bit is b0. For the main divider ratio, the first bit (b5) is the Most Significant Bit (MSB).

The serial bus enable (S\_EN) must be LOW to capture new programming data and must be HIGH to switch on the synthesizer.

### Receiver

The receiver is a fully integrated RF + IF strip and demodulator for DECT. It provides all the required channel filtering over the DECT band and generates analog RSSI and a switched output for Philips Semiconductors baseband chip. Very few off-chip components are required and all of these can be placed without trimming. The chip is designed to operate with a power supply voltage that can fall to 3.0 V. The input is the RF antenna signal derived from the band filter or the antenna switch. The outputs are the RSSI voltage, representing the instantaneous signal strength and two HIGH-level demodulator output signals RDATAP and DATAM, the latter being switched by SLCCTR to generate the external slicer threshold. During the blind slot, while the PLL is settling, an internal voltage source is activated to precharge the external capacitor (connected to pin DATAM) to a voltage close to the required slicer threshold.

### **Operating modes**

The operating modes available are:

- Normal mode (see Fig.3)
- Reduced signal mode (see Fig.4)
- Advanced signal mode (see Fig.5).

Selection of an operating mode is achieved via the serial interface register (see Table 3).

### NORMAL MODE (MODE 1)

In the normal mode, the synthesizer is ON when S\_EN = HIGH and VCO\_ON = HIGH, and OFF when S\_EN = LOW. When turned ON, the dividers and phase detector are synchronized to avoid a random initial phase error. When turned OFF, the phase detector is synchronized with the dividers to avoid interrupting a charge-pump pulse. This feature requires a signal to be present for a few microseconds on the XTAL pin after S\_EN goes LOW.

The VCO is ON when the input signal VCO\_ON is HIGH. The polarity of VCO\_ON is chosen for compatibility with output S\_PWR of the baseband chip. When the VCO is turned ON, it takes 50  $\mu$ s (typical) to reach its steady state.

The TX preamplifier is ON when bit 'TRX' is programmed to '0' and VCO\_ON is HIGH. When the TX preamplifier is turned ON, it takes typically 10  $\mu$ s to be ready. The receiver is turned ON when R\_ON = HIGH and VCO\_ON = HIGH.

### REDUCED SIGNAL MODE (MODE 2)

In the reduced signal mode, the parallel control signals are replaced by serial bus programming. To select this mode, the bit 'NEW' of the internal register must be set to '1' and the bit 'SPWR' must be reset to '0', timing is then controlled by the S\_EN signal.

After the register programming, the S\_EN rising edge programs the PLL, closes the loop, powers-on the VCO and, if the 'TRX' bit = 0, turns ON the TX preamplifier. On the falling edge of the first S\_EN pulse, the loop is opened (unless the bit 'PLL' is set to 1) and the receiver switches ON if the 'TRX' bit = 1. A second pulse on S\_EN is required at the end of the wanted slot to power-down the application.

The R\_ON pin becomes an output in this mode, drives the RX PIN diode and corresponds to the internal power-on signal of the receiver.

### ADVANCED SIGNAL MODE (MODE 3)

In the advanced signal mode, the parallel control signals are partly replaced by serial bus programming. To select this mode, the bit 'NEW' and the bit 'SPWR' of the internal register must be set to '1'. The S\_EN signal will then control the UAA3545 timing (except for timing of a general power-down as this is controlled by the VCO\_ON input).

The VCO\_ON signal should rise at the beginning of the previous slot. After the serial bus has been programmed, the S\_EN rising edge programs the PLL, closes the loop and, if the 'TRX' bit = 0, turns ON the TX preamplifier. On the falling edge of the first S\_EN pulse, the loop is opened (unless the 'PLL' bit is set to 1) and the RX section switches ON if bit 'TRX' = 1. At the end of the wanted slot, the VCO\_ON goes LOW to power-down the whole IC. In fact, the second pulse of the S\_EN signal in mode 2 is now replaced by the signal VCO\_ON.

The R\_ON pin becomes an output in this mode, drives the RX PIN diode and corresponds to the internal power-on signal of the receiver.

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### Programming

### Table 1 Serial interface register

	REGISTER BIT ALLOCATION									
first in	first in last in									
b23 to b20	b19	b18, b17	b16 to b10	b9	b8	b7	b6	b5 to b0 <sup>(1)</sup>		
TEST <sup>(2)</sup>	SLIC <sup>(3)</sup>	REFD <sup>(4)</sup>	TEST <sup>(2)</sup>	SPWR <sup>(5)</sup>	PLL <sup>(6)</sup>	NEW <sup>(5)</sup>	TRX	MAIN DIVIDER <sup>(7)</sup>		

### Notes

- 1. Bit b5 is the MSB of the main divider coefficient; this comprises bits b5, b4, b3, b2, b1, b0 and b6 (TRX).
- 2. Test bits b23, b22, b21, b20, b16, b15, b14, b13, b12, b11, b10 must always be programmed to 0.
- 3. Bit 'SLIC' = 1 forces the internal slicer on. In this mode, pin DATAM is connected to an external capacitor. Together with an internal 1 kΩ resistor, it defines the low pass time constant for the slicer threshold voltage. When the bit 'SLIC' = 0, the pin RDATAP is connected directly to the demodulator output and delivers an analog signal. Pin DATAM also reflects the demodulator voltage without the internal 1 kΩ resistor when the SLCCTR pin is HIGH.
- 4. REFD sets the reference divider ratio to 4, 8, 12 or 16 (corresponding respectively to a reference input frequency of 3.456, 6.912, 10.368 or 13.824 MHz) (see Table 4).
- 5. Bits 'NEW', and 'SPWR' select the operating mode (see Table 3).
- 6. Bit 'PLL' = 1 forces the PLL to remain on when the VCO is on.
- 7. The main divider ratio is equal to 2176 + the programmed value (see Table 2).

### Table 2 Main divider programming

	BIT							SYNTHESIZED
b5	b4	b3	b2	b1	b0	b6 (TRX)	RATIO	FREQUENCY (MHz)
	Binary equivalent of n						2176 + n	0.864 × (2176 + n)
0	0	0	0	0	0	0	2176	1880.064
0	1	0	1	1	1	1	2223	1920.672

### Table 3 Operating mode selection

BIT		OPERATING MODE		
b9 (SPWR)	b7 (NEW)	OPERATING MODE		
0	0	normal mode (mode 1)		
0	1	reduced signal mode (mode 2)		
1	0	do not use		
1	1	advanced signal mode (mode 3)		

 Table 4
 Reference divider ratio programming

B	ыт	REFERENCE DIVIDER RATIO	REFERENCE INPUT FREQUENCY		
b18	b17	REFERENCE DIVIDER RATIO	REFERENCE INFOT FREQUENCY		
0	0	4	3.456 MHz		
0	1	16	13.824 MHz		
1	0	8	6.912 MHz		
1	1	12	10.368 MHz		

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### LIMITING VALUES

In accordance with the Absolute Maximum Rating System (IEC 60134).

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
$V_{CC(syn)}, \\ V_{CC(reg)}, \\ V_{CC(RX)}, \\ V_{CC(TX)}$	supply voltage	All $V_{CC}$ supplies must be at the same potential ( $V_{CC}$ )	-0.3	+3.6	V
V <sub>n</sub>	voltage on any pin		-0.3	V <sub>CC</sub>	V
P <sub>i(RFA)(max)</sub> , P <sub>i(RFB)(max)</sub>	maximum input power at pins RFA and RFB		-	15	dBm
∆GND	difference in ground supply voltage applied between all ground pins	note 1	-	0.01	V
P <sub>tot</sub>	total power dissipation		-	300	mW
T <sub>stg</sub>	storage temperature		-55	+125	°C
T <sub>amb</sub>	ambient temperature		-10	+60	°C
Tj	junction temperature		-	150	°C

### Note

1. Ground pins must be short-circuited externally (this is in addition to being short-circuited internally.

### HANDLING

Inputs and outputs are protected against electrostatic discharge in normal handling. However, to be totally safe, it is desirable to take normal precautions appropriate to handling MOS devices.

All pins are compatible with "EIA/JESD22-A114-A Class1 (October 1997)".

### LATCH-UP

Pins S\_DATA, TXA and TXB are susceptible to latch-up if a negative current greater than 20 mA is drawn from the respective pin (occurs when the pin voltage is negative with respect to GND).

To avoid latch-up, pins TXA and TXB pins must be connected to  $V_{CC}$  through coils, and the S\_DATA control signal input from the baseband IC must be kept positive with respect to GND.

### THERMAL CHARACTERISTICS

SYMBOL	PARAMETER	CONDITIONS	VALUE	UNIT
R <sub>th(j-a)</sub>	thermal resistance from junction to ambient	in free air	100	K/W

# UAA3545

# CHARACTERISTICS

 $V_{CC}$  = 3.2 V;  $T_{amb}$  = 25 °C;  $f_{dev}$  = 288 kHz;  $f_{(i)XTAL}$  = 13.824 MHz; characteristics with a typical value only are not tested; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Supplies						
$V_{CC(syn)}, \\ V_{CC(reg)}, \\ V_{CC(RX)}, \\ V_{CC(TX)}$	supply voltage	All $V_{CC}$ supplies must be at the same potential ( $V_{CC}$ )	3.0	3.2	3.6	V
I <sub>CC(SYN)</sub>	synthesizer supply current	S_EN = HIGH	_	5	7	mA
I <sub>CC(REG)</sub>	VCO, buffer and prescaler regulator supply current	VCO ON	-	14	17	mA
I <sub>CC(RX)</sub>	receiver supply current	RX mode	-	36	44	mA
I <sub>CC(TX)</sub>	transmit preamplifier supply current	TX mode	-	12	15	mA
I <sub>CC(pd)</sub>	total supply current in Power-down mode		-	10	100	μA
Synthesize	r	•			•	
	R					
f <sub>o(RF)</sub>	RF output frequency		1880	_	1930	MHz
R <sub>m</sub>	main divider ratio		2176	_	2234	
REFERENCE	DIVIDER	•				•
f <sub>(i)XTAL</sub>	crystal reference input frequency	programmed values; see Table 4	-	3.456, 6.912, 10.368 or 13.824	_	MHz
V <sub>(i)XTAL(p-p)</sub>	crystal reference input voltage (peak-to-peak value)	square wave input; all f <sub>(i)XTAL</sub> values	1.2	-	1.8	V
R <sub>RD</sub>	reference divider ratio	programmed values; see Table 4	-	4, 8, 12 or 16	_	
R <sub>i(XTAL)</sub>	input resistance (real part of the parallel input impedance)	f <sub>(i)XTAL</sub> = 3.456 MHz	-	17	-	kΩ
C <sub>i(XTAL)</sub>	input capacitance (imaginary part of the parallel input impedance)	f <sub>(i)XTAL</sub> = 3.456 MHz	-	1.5	-	pF
PHASE COMP	PARATOR					
f <sub>PC</sub>	phase comparator frequency		-	864	_	kHz

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
CHARGE-PUM	IP OUTPUT					
I <sub>o(CP)</sub>	charge-pump output current	$V_{CP} = \frac{1}{2}V_{CC}$	-	3.5	-	mA
VCO	1		1	-	- 1	
f <sub>VCO</sub>	oscillator frequency	defined at transmit output, $T_{amb} = -10$ to +60 °C; note 1	1880	-	1930	MHz
V <sub>CP/VCOtune</sub>	charge pump input voltage and VCO tuning output voltage		0.3	-	V <sub>CC</sub> - 0.3	V
G <sub>VCO</sub>	VCO tuning input gain (mean value)	defined at transmit output; note 2	-	70	-	MHz/V
G <sub>MOD</sub>	VCO modulation input gain	defined at transmit output; note 3	-	2.4	-	MHz/V
Transmit pr	eamplifier				·	
P <sub>o(TXA)</sub> , P <sub>o(TXB)</sub>	transmit output power	$T_{amb} = -10$ to +60 °C; $f_{VCO} = 1880$ to 1930 MHz; note 1	0	3	-	dBm
R <sub>o(TXA)</sub> , R <sub>o(TXB)</sub>	transmit output resistance (real part of the parallel output impedance)	balanced; expressed at high signal level	-	200	-	Ω
$\begin{array}{c} C_{o(TXA)},\\ C_{o(TXB)} \end{array}$	transmit output capacitance (imaginary part of the parallel output impedance)	balanced; expressed at high signal level	-	0.3	-	pF
f <sub>VCO(feedthru)</sub>	VCO frequency feedthrough at transmit output	referred to $P_{o(TXA)}$ , $P_{o(TXB)}$ ; $f_{VCO} = 1900 \text{ MHz}$ ; note 1	-	-20	-15	dBc
CNR <sub>25</sub>	carrier-to-noise ratio at transmit output	carrier offset in closed loop; $\Delta f = 25 \text{ kHz}$	-	-65	-56	dBc/Hz
CNR <sub>4686</sub>	carrier-to-noise ratio at transmit output	carrier offset; ∆f = 4686 kHz	-	-135	-129	dBc/Hz
$\Delta f_{o(push)}$	frequency shift due to supply voltage drop	measured dynamically; $V_{CC}$ drop = 100 mV; $V_{CP/VCOtune} = 1.2$ V; $V_{MOD} = 0$ ; TX load = 50 $\Omega$ ; note 1	_	+10	±20	kHz
∆f <sub>o(pull)</sub>	frequency shift due to disabling the synthesizer	frequency pulling measured 20 $\mu$ s after synthesizer disabled; V <sub>CP/VCOtune</sub> set by the PLL on f <sub>VCO</sub> = 1880.064 MHz; V <sub>MOD</sub> = 0; TX load = 50 $\Omega$ ; note 1	-	+5	±10	kHz
$\Delta f_{o(drift)}$	transmit output frequency drift during a slot	notes 1 and 4	-	-6	±12	kHz

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Receiver se	ection			-1		
V <sub>RSSI(max)</sub>	maximum RSSI output voltage	under high RX input signal level	-	1.9	-	V
V <sub>RSSI</sub>	RSSI output voltage	monotonicity over range –96 to –36 dBm				
		$P_{i(RFA/B)} = -33 \text{ dBm}$	-	1.7	2.0	V
		$P_{i(RFA/B)} = -36 \text{ dBm}$	-	1.64	_	V
		$P_{i(RFA/B)} = -96 \text{ dBm}$	-	0.3	_	V
t <sub>on</sub>	wake-up time from the power-on signal to correct RSSI output		-	25	40	μs
SB	input sensitivity	BER ≤ 10 <sup>-3</sup> ; note 1	-	-96	-93	dBm
		BER ≤ 10 <sup>-5</sup> ; note 1	_	-92	-76	dBm
IM	intermodulation rejection	BER < $10^{-3}$ ; wanted signal at -83 dBm; level of interference in channels n + 2 and n + 4; note 1	33	42	_	dBc
R <sub>co</sub>	co-channel rejection	BER < $10^{-3}$ ; wanted channel at -76 dBm; note 1	-10	-7.5	-	dBc
R <sub>i(n-1)</sub>	adjacent channel rejection	BER < $10^{-3}$ ; wanted channel at -76 dBm; adjacent level referred to wanted channel level; note 1	14	20	-	dBc
R <sub>i(n-2)</sub>	bi-adjacent channel rejection	BER < $10^{-3}$ ; wanted channel at -76 dBm; bi-adjacent level referred to wanted channel level; note 1	35	42	-	dBc
R <sub>i(n−≥3)</sub>	rejection with ≥3 channels separation	BER < $10^{-3}$ ; wanted channel at -76 dBm; n ≥ 3 adjacent level referred to wanted channel level; note 1	40	45	_	dBc
RBI	rejection of a blocking signal	BER < 10 <sup>−3</sup> ; wanted signal at –83 dBm at channel 5:				
		$ f - f_c  > 6 MHz$ ; note 2	38	55	_	dBc
		(f <sub>RFmax</sub> + 5 MHz) < f < 2 GHz; 1780 MHz < f < (f <sub>RFmin</sub> – 5 MHz) ; note 1	48	58	-	dBc
		2 GHz < f < 4.32 GHz; notes 1 and 5	38	60	-	dBc
R <sub>o(RF)</sub>	RF input resistance (real part of the parallel input impedance)	balanced; at 1890 MHz	-	100	-	Ω
$C_{o(RF)}$	RF input capacitance (imaginary part of the parallel input impedance)	balanced; at 1890 MHz	-	0.8	_	pF

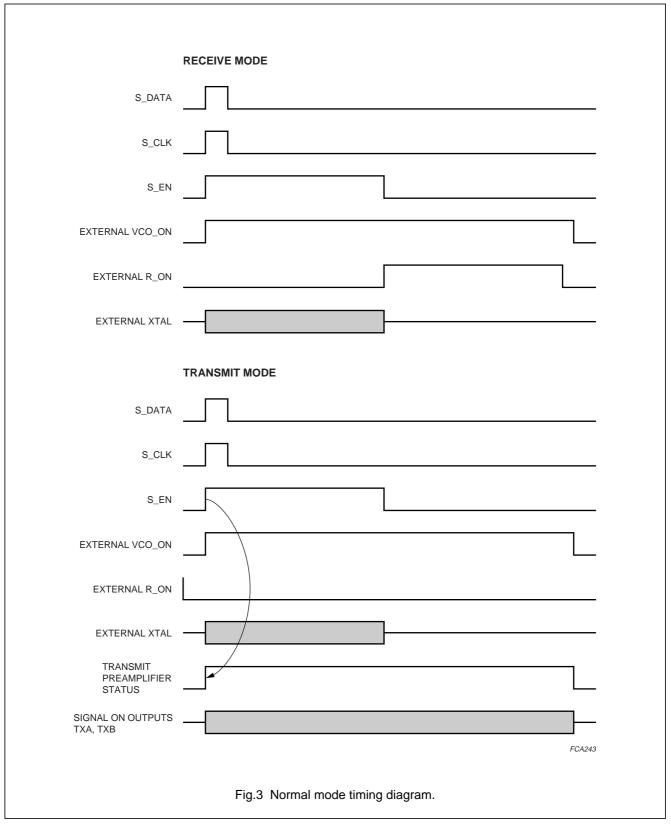
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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
f <sub>i(RF)(max)</sub>	maximum RF input frequency		_	-	1930	MHz
f <sub>i(RF)(min)</sub>	minimum RF input frequency		1880	-	-	MHz
RL <sub>RF</sub>	return loss on matched RF input	balanced; note 1	11	15	-	dB
G <sub>DEM</sub>	demodulator gain	mean value of $f_{dev} = \pm 288 \text{ kHz}$	_	1.6	_	V/MHz
V <sub>DEM</sub>	DC level at demodulator outputs RDATAP and DATAM	f <sub>LO</sub> = f <sub>RF</sub> + 864 kHz	-	1.3	-	V
Interface log	gic input and output pins	S_DATA, S_CLK, S_EN, R_ON, V	CO_ON, SL	CCTR an	d RDATAP	
V <sub>IH</sub>	HIGH-level input voltage	note 6	1.4	-	V <sub>CC</sub>	V
V <sub>IL</sub>	LOW-level input voltage)		-0.3	-	+0.4	V
I <sub>bias</sub>	input bias current	HIGH or LOW input levels	-5	-	+5	μA
V <sub>OH(RDATAP)</sub>	HIGH-level output voltage (pin RDATAP)	bit 'SLIC' = 1; I <sub>OH</sub> = 500 μA	V <sub>CC</sub> - 0.4	V <sub>CC</sub>	-	V
V <sub>OL(RDATAP)</sub>	LOW-level output voltage (pin RDATAP)	bit 'SLIC' = 1; I <sub>OL</sub> = -500 μA	-	0	0.4	V
I <sub>O(RON)</sub>	output drive current (pin R_ON)	mode 2 or 3; $V_{RON}$ = HIGH level; $V_{CC} - V_{RON}$ = 0.5 V	2.5	5	-	mA
Z <sub>O(RON)</sub>	output impedance (pin R_ON)	mode 2 or 3; V <sub>RON</sub> = LOW level	_	6	-	kΩ
f <sub>SCLK(max)</sub>	maximum frequency (pin S_CLK)		-	10	-	MHz
t <sub>SEN(min)</sub>	minimum pulse duration (pin S_EN)		-	1	-	μs

### Notes

- 1. Measured and guaranteed only on the Philips evaluation board, including Printed-Circuit Board (PCB) and balun filter with internal slicer.
- 2. Mean of the values of transmit frequency at V<sub>CP/VCOtune</sub> = 0.3 and 2.7 V.
- 3. Measured with  $V_{CP/VCOtune} = 1.5$  V, mean of the values of transmit frequency at  $V_{MOD} = 0$  and 0.5 V.
- 4. Frequency difference measured during 420  $\mu$ s with V<sub>MOD</sub> = 0 (no modulation applied), at least 20  $\mu$ s after disabling the synthesizer.
- 5. Except for three occurrences, as defined in the DECT specification.
- 6.  $V_{\text{IH}}$  should never exceed 3.6 V.

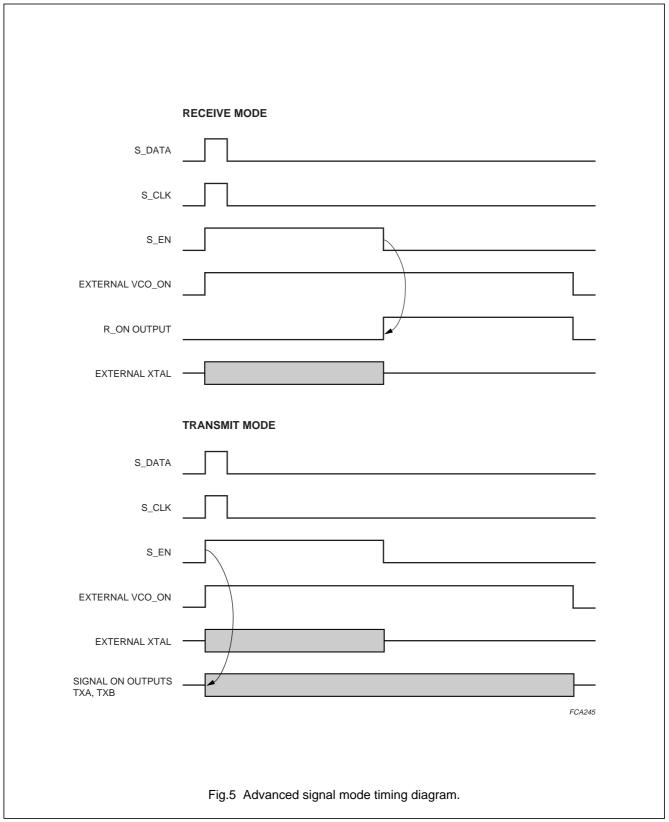
# **MODE 1 TIMING**



# **MODE 2 TIMING**

	RECEIVE MODE
S_DATA	
S_CLK	
S_EN	
INTERNAL VCO_ON	
R_ON OUTPUT	
EXTERNAL XTAL	
	TRANSMIT MODE
S_DATA	
S_DATA S_CLK	
S_CLK	
S_CLK S_EN	
S_CLK S_EN INTERNAL VCO_ON	
S_CLK S_EN INTERNAL VCO_ON EXTERNAL XTAL SIGNAL ON OUTPUTS	TRANSMIT MODE
S_CLK S_EN INTERNAL VCO_ON EXTERNAL XTAL SIGNAL ON OUTPUTS	

# **MODE 3 TIMING**

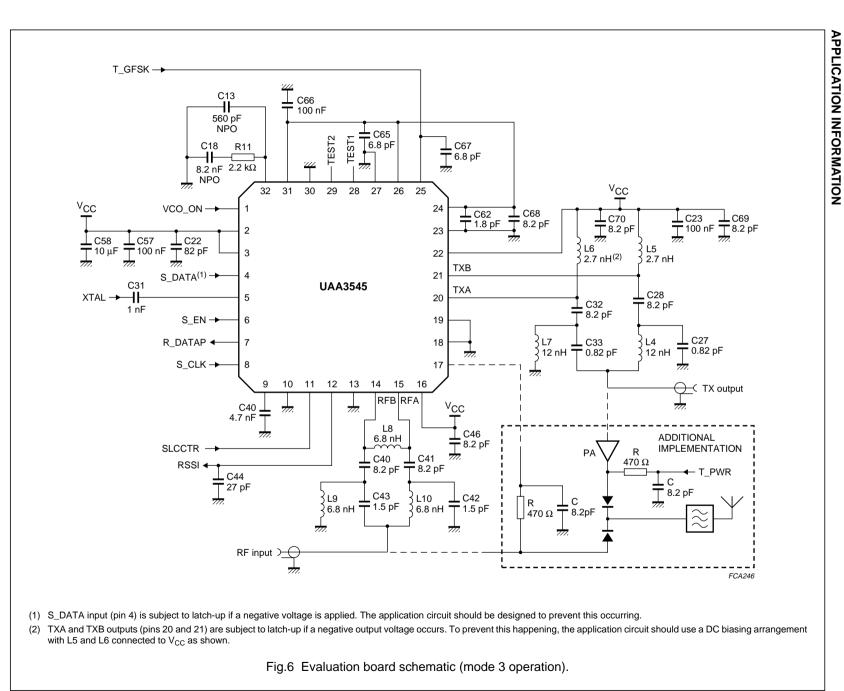


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# **DECT** transceiver

# UAA3545



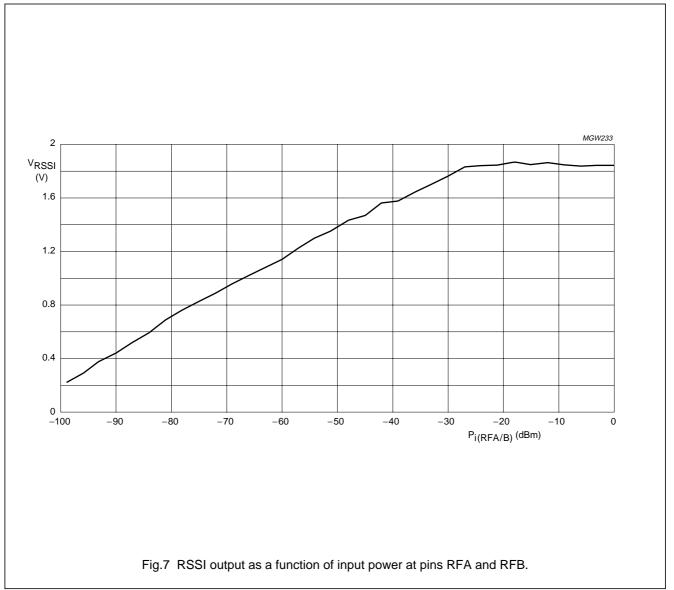
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Internal	pin	configuration
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PIN	SYMBOL	INTERNAL CIRCUIT	
1	VCO_ON		
4	S_DATA		
6	S_EN		
8	S_CLK		
11	SLCCTR		
7	RDATAP		
9	DATAM	(7,9)	
12	RSSI		
14	RFB		
15	RFA		
17	R_ON		

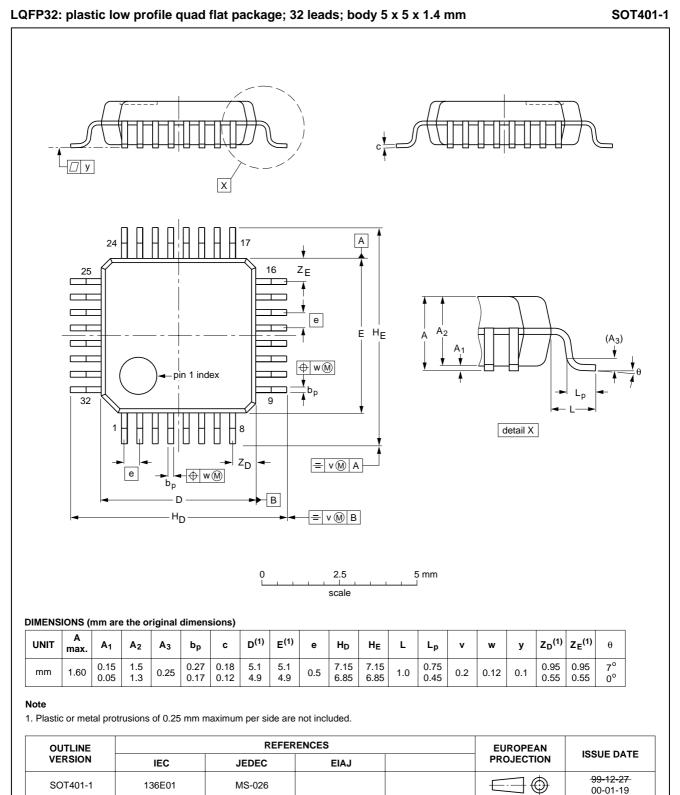
# PIN SYMBOL **INTERNAL CIRCUIT** 20 TXA ТХВ 21 21) MGW240 25 V<sub>MOD</sub> MGW241 31 VREGO (31) MGW242 L CP/VCO<sub>tune</sub> 32 MGW243

# **RECEIVED SIGNAL STRENGTH INTENSITY**



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### PACKAGE OUTLINE



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### SOLDERING

### Introduction to soldering surface mount packages

This text gives a very brief insight to a complex technology. A more in-depth account of soldering ICs can be found in our *"Data Handbook IC26; Integrated Circuit Packages"* (document order number 9398 652 90011).

There is no soldering method that is ideal for all surface mount IC packages. Wave soldering can still be used for certain surface mount ICs, but it is not suitable for fine pitch SMDs. In these situations reflow soldering is recommended.

### **Reflow soldering**

Reflow soldering requires solder paste (a suspension of fine solder particles, flux and binding agent) to be applied to the printed-circuit board by screen printing, stencilling or pressure-syringe dispensing before package placement.

Several methods exist for reflowing; for example, convection or convection/infrared heating in a conveyor type oven. Throughput times (preheating, soldering and cooling) vary between 100 and 200 seconds depending on heating method.

Typical reflow peak temperatures range from 215 to 250 °C. The top-surface temperature of the packages should preferable be kept below 220 °C for thick/large packages, and below 235 °C for small/thin packages.

### Wave soldering

Conventional single wave soldering is not recommended for surface mount devices (SMDs) or printed-circuit boards with a high component density, as solder bridging and non-wetting can present major problems.

To overcome these problems the double-wave soldering method was specifically developed.

If wave soldering is used the following conditions must be observed for optimal results:

- Use a double-wave soldering method comprising a turbulent wave with high upward pressure followed by a smooth laminar wave.
- For packages with leads on two sides and a pitch (e):
  - larger than or equal to 1.27 mm, the footprint longitudinal axis is preferred to be parallel to the transport direction of the printed-circuit board;
  - smaller than 1.27 mm, the footprint longitudinal axis must be parallel to the transport direction of the printed-circuit board.

The footprint must incorporate solder thieves at the downstream end.

• For packages with leads on four sides, the footprint must be placed at a 45° angle to the transport direction of the printed-circuit board. The footprint must incorporate solder thieves downstream and at the side corners.

During placement and before soldering, the package must be fixed with a droplet of adhesive. The adhesive can be applied by screen printing, pin transfer or syringe dispensing. The package can be soldered after the adhesive is cured.

Typical dwell time is 4 seconds at 250 °C. A mildly-activated flux will eliminate the need for removal of corrosive residues in most applications.

### Manual soldering

Fix the component by first soldering two diagonally-opposite end leads. Use a low voltage (24 V or less) soldering iron applied to the flat part of the lead. Contact time must be limited to 10 seconds at up to 300 °C.

When using a dedicated tool, all other leads can be soldered in one operation within 2 to 5 seconds between 270 and 320  $^\circ\text{C}.$ 

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### Suitability of surface mount IC packages for wave and reflow soldering methods

PACKAGE	SOLDERING METHOD		
FACRAGE	WAVE	REFLOW <sup>(1)</sup>	
BGA, HBGA, LFBGA, SQFP, TFBGA	not suitable	suitable	
HBCC, HLQFP, HSQFP, HSOP, HTQFP, HTSSOP, HVQFN, SMS	not suitable <sup>(2)</sup>	suitable	
PLCC <sup>(3)</sup> , SO, SOJ	suitable	suitable	
LQFP, QFP, TQFP	not recommended <sup>(3)(4)</sup>	suitable	
SSOP, TSSOP, VSO	not recommended <sup>(5)</sup>	suitable	

### Notes

- 1. All surface mount (SMD) packages are moisture sensitive. Depending upon the moisture content, the maximum temperature (with respect to time) and body size of the package, there is a risk that internal or external package cracks may occur due to vaporization of the moisture in them (the so called popcorn effect). For details, refer to the Drypack information in the "Data Handbook IC26; Integrated Circuit Packages; Section: Packing Methods".
- 2. These packages are not suitable for wave soldering as a solder joint between the printed-circuit board and heatsink (at bottom version) can not be achieved, and as solder may stick to the heatsink (on top version).
- 3. If wave soldering is considered, then the package must be placed at a 45° angle to the solder wave direction. The package footprint must incorporate solder thieves downstream and at the side corners.
- 4. Wave soldering is only suitable for LQFP, TQFP and QFP packages with a pitch (e) equal to or larger than 0.8 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.65 mm.
- 5. Wave soldering is only suitable for SSOP and TSSOP packages with a pitch (e) equal to or larger than 0.65 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.5 mm.

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### DATA SHEET STATUS

DATA SHEET STATUS <sup>(1)</sup>	PRODUCT STATUS <sup>(2)</sup>	DEFINITIONS
Objective specification	Development	This data sheet contains data from the objective specification for product development. Philips Semiconductors reserves the right to change the specification in any manner without notice.
Preliminary specification	Qualification	This data sheet contains data from the preliminary specification. Supplementary data will be published at a later date. Philips Semiconductors reserves the right to change the specification without notice, in order to improve the design and supply the best possible product.
Product specification	Production	This data sheet contains data from the product specification. Philips Semiconductors reserves the right to make changes at any time in order to improve the design, manufacturing and supply. Changes will be communicated according to the Customer Product/Process Change Notification (CPCN) procedure SNW-SQ-650A.

### Notes

- 1. Please consult the most recently issued data sheet before initiating or completing a design.
- 2. The product status of the device(s) described in this data sheet may have changed since this data sheet was published. The latest information is available on the Internet at URL http://www.semiconductors.philips.com.

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**Short-form specification** — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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